

Abstract boundary systems and application to flow in networks with memory

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Flows in networks with delay in the vertices

$$(1) \begin{cases} \frac{d}{dt} u_j(x, t) = \frac{d}{dx} u_j(x, t), & t \geq 0, x \in (0, 1), \\ u_j(x, 0) = f_j(x), & x \in (0, 1), \\ \phi_{ij}^- u_j(1, t) = \omega_{ij} \sum_{k \in J} \phi_{ik}^+ [u_k(0, t) + L_k(u_k(\cdot, t + \cdot))], & t \geq 0, \\ u_j(x, \tau) = g_j(x, \tau), & x \in (0, 1), \tau \in [-1, 0], \end{cases}$$

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for $i \in I := \{1, \dots, p\}$, $j \in J := \{1, \dots, n\}$. Here, $\Phi^- = (\phi_{ij}^-)_{p \times n}$ and $\Phi^+ = (\phi_{ij}^+)_{p \times n}$ are the *outgoing* and *incoming incidence matrix* of the directed graph G , respectively.

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for all $f = (f_k)_{k=1}^n \in W := W^{1,1}([0, 1], \mathbb{C}^n)$ and $g = (g_k)_{k=1}^n \in W^{1,1}([-1, 0], W)$,

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$$D(A_m) := W^{1,1}([0, 1], \mathbb{C}^n) \text{ and } A_m := \frac{d}{dx},$$

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and on $X \times Y$

$$D(\mathcal{A}_{\mathbb{B}}) = \left\{ \begin{pmatrix} f \\ g \end{pmatrix} \in D(A_m) \times D(B_m) : \right. \\ \left. f(1) - \mathbb{B}f(0) = \mathbb{B}L(g), f = g(0) \right\}$$

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Using semigroup theory and perturbation techniques one proves the wellposedness of (ACP) and hence of (1).

Spectrum

Define the matrix

$$\mathbb{B}_\lambda := e^{-\lambda} \mathbb{B}(I + L_\lambda), \quad \lambda \in \mathbb{C},$$

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$$\lambda \in \sigma(\mathcal{A}_{\mathbb{B}}) \iff 1 \in \sigma(\mathbb{B}_\lambda) \iff \lambda \in P\sigma(\mathcal{A}_{\mathbb{B}}).$$

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where P is the spectral projection of rank one corresponding to the spectral value $s(\mathcal{A}_{\mathbb{B}})$, and $(\mathcal{T}_{\mathbb{B}}(t))_{t \geq 0}$ is the semigroup solution to (ACP).

Flow in networks with memory

$$(2) \left\{ \begin{array}{l} \frac{d}{dt} u_j(x, t) = \frac{d}{dx} u_j(x, t) + \sum_{k \in J} D_{jk}(u_k(x, \cdot + t)), \quad t \geq 0, x \in (0, 1) \\ u_j(x, 0) = f_j(x), \quad x \in (0, 1), \\ \phi_{ij}^- u_j(1, t) = \omega_{ij} \sum_{k \in J} \phi_{ik}^+ [u_k(0, t) + L_k(u_k(\cdot, t + \cdot))], \quad t \geq 0, \\ u_j(x, \tau) = g_j(x, \tau), \quad x \in (0, 1), \tau \in [-1, 0], \end{array} \right.$$

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for $i \in I := \{1, \dots, p\}$, $j \in J := \{1, \dots, n\}$.

Here

$$L_k(g_k) = \int_{-1}^0 d\nu_k(\theta) g_k(\theta), \quad D_{jk}(g_k) = \int_{-1}^0 d\mu_{jk}(\theta) g_k(\theta)$$

for $g = (g_k) \in W^{1,1}([-1, 0], X)$, where

$\mu = (\mu_{jk}) : [-1, 0] \rightarrow \mathcal{L}(X)$ and $\nu = (\nu_k) : [-1, 0] \rightarrow \mathcal{L}(X, \mathbb{C}^n)$ are BV.

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$\mu = (\mu_{jk}) : [-1, 0] \rightarrow \mathcal{L}(X)$ and $\nu = (\nu_k) : [-1, 0] \rightarrow \mathcal{L}(X, \mathbb{C}^n)$ are BV. Note that the above operators are no more bounded on $L^1([-1, 0], X)$.

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Here

$$\begin{aligned} G, M &: W^{1,1}([0, 1], \mathbb{C}^n) \rightarrow \mathbb{C}^n; \\ Gf &= f(1), \quad Mf = \mathbb{B}f(0), \quad f \in W^{1,1}([0, 1], \mathbb{C}^n). \end{aligned}$$

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As in the first part (2) can be transformed as

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The classical perturbation theory doesn't work for $\mathcal{A}_{0,L}$, since the delay operator L is unbounded. One needs a so-called Staffans-Weiss closed loop systems.

Staffans-Weiss perturbations

Assumptions:

- (H1)** the operator $A \subset A_m$ with domain $D(A) = \ker(G)$ generates a C_0 -semigroup $(T(t))_{t \geq 0}$ on X ;
- (H2)** $G : Z \rightarrow \partial X$ is surjective;

Using **(H1)** and **(H2)**, we can define the "Dirichlet" operator

$$\begin{aligned}\mathbb{D}_\lambda &= G_{|\ker(\lambda - A_m)}^{-1} \in \mathcal{L}(\partial X, Z), \\ B &= (\lambda - A_{-1})\mathbb{D}_\lambda \in \mathcal{L}(\partial X, X_{-1}), \lambda \in \rho(A),\end{aligned}$$

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We also assume that

- (H3)** the triple operator (A, B, C) generates a regular linear system on $X, \partial X, \partial X$ with the identity operator $I_{\partial X}$ as admissible feedback.

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$\mathcal{A}_{0,L}$ generates C_0 -semigroup on $X \times Y$.

References

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