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Forecasting Interest Rate Volatility of the United Kingdom: Evidence from over 150 Years of Data

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Abstract

This study examines the very short, short, medium and long-term forecasting ability of different univariate GARCH models of United Kingdom (UK)'s interest rate volatility, using a long span monthly data from May 1836 to June 2018. The main results show the relevance of considering alternative error distributions to the normal distribution when estimating GARCH-type models. Thus, we obtain that the Asymmetric Power ARCH (A-PARCH) models with skew generalized error distribution are the most accurate models when forecasting UK interest rates, while for the short, medium and long-term forecasting horizons ($h=3$ and $h=6$, $h=12$), GARCH models with generalized error distribution for the error term are the most accurate models in forecasting UK's interest rates.

Keywords: interest rates; volatility; GARCH models; forecasting; error distributions

JEL: C22; C53; G17.

1. Introduction

2 While UK interest rates were very stable during the 19th century and until
3 World War I, the evolution of interest rates in the twentieth century showed

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4 periods of large increases and decreases, that is, periods of high volatility.
5 For example, interest rates reached their highest level (17%) in 1979, after a
6 decision of the conservative government to combat inflation after the oil price
7 shock, and it also increased to 15% at the beginning of the 1990s to keep the
8 value of the pound fixed in the European Exchange Rate Mechanism. These
9 increases in interest rates were followed by the recessions occurred in UK in
10 1980/81 and 1991/92. On the other hand, in the context of the financial
11 crisis, interest rates fell to their lowest levels in 300 years, reaching a level of
12 0.25% in 2016. Interest rates are not only a key tool of monetary policy, but
13 they have also important implications on many economic variables, such as
14 investment rate, economic growth, stock returns, or exchange rates, among
15 others (Bernanke, 1983). Furthermore, interest rate volatility can be taken as
16 an indicator of uncertainty and risk, and it is fundamental to price securities,
17 which justifies the numerous attempts to model and forecast interest rates
18 and their volatility. In this context, modelling and forecasting the interest
19 rate volatility will be important from a monetary policy view (Walsh, 1984;
20 Chadha and Nolan, 2001; Bartolini et al., 2002) and also for portfolio diver-
21 sification (Barnhill and Maxwell, 2002), for risk managers and for hedging
22 strategies (Carcano and Foresi, 1997; Chan et al., 2001).

23 An extensive number of papers on modelling interest rate volatility can be
24 found in the literature. As it happens with most of the financial series, mod-
25 elling interest rates requires to take into account the following characteristics
26 usually observed in these variables, such as volatility clustering, excess kurto-
27 sis, asymmetric effects, non-linearities, time varying volatility and volatility
28 clustering, long-memory or leverage effect (Franses and Dijk, 2000; Zumbach,
29 2013). In a seminal paper by Chan et al. (1992), for example, the authors
30 assume that UK interest rate volatility is sensitive to interest rate levels -level
31 effect-, while Brenner et al. (1996) and Koedijk et al. (1997) propose a model
32 for the interest rate volatility that takes into account not only the level effect
33 in Chan et al. (1992) but also the conditional heteroscedasticity effect of the
34 Generalized Autoregressive Conditional Heteroskedasticity (GARCH) type
35 models (Engle, 1982; Bollerslev, 1986), which explains the extensive use of
36 these models to model interest rates (Longstaff and Schwartz, 1992). How-
37 ever, as conventional GARCH type models cannot account for asymmetries,
38 new models such as Exponential GARCH (EGARCH) models (Nelson, 1991)

39 or Asymmetric Power ARCH (APARCH) models (Ding et al., 1993) or GJR-
40 GARCH models were introduced to model and forecast interest rates (Bali,
41 2000). Furthermore, since the distribution of the innovations in these mod-
42 els is far from a normal (Drost and Klaasen, 1997), and usually unknown,
43 semiparametric techniques can be used to model financial variables. Hou and
44 Suardi (2011), for example, use a semiparametric smoothing technique to the
45 GARCH model of short rate volatility to forecast US short-term interest rate
46 volatility and obtain that this approach produces more accurate estimates
47 of interest rate volatility than other parametric models. Tian and Hamori
48 (2015) model the short-term interest rate in the euro-yen market using the
49 Realized GARCH (RGARCH) model in order to capture the volatility clus-
50 tering and the mean reversion effects of interest rate behaviour, and find that
51 this model outperforms conventional GARCH-type models.

52 As such, the objective of the paper is to examine the short and long-term
53 forecasting ability of UK interest volatility of different univariate General-
54 ized Autoregressive Conditional Heteroscedasticity (GARCH) models, using
55 monthly data from May 1836 to June 2018. The contributions of the pa-
56 per are the following. First, we analyse the forecasting accuracy of a wide
57 number of GARCH models in order to take into account the time series
58 characteristics of interest rates and their volatility. When using GARCH
59 models, we try to capture the heavy tailed and asymmetric behaviour using
60 alternative error term distributions, such as Normal, Students t, Generalized
61 Error Distribution (GED), Skew Normal (SN), Skew Students (SSt), Skew
62 Generalized Error Distribution (SGED), Inverse Gaussian (IG), Generalized
63 Hyperbolic (GH) and Johnsons SU Distribution (JSU). Furthermore, the
64 ARMA-Generalized Additive Semiparametric GARCH by Hou and Suardi
65 (2011) and the Mixture Autoregressive Model by Wong and Li (2000) are
66 also used to forecast UK interest rates. Finally, the analysis covers the time
67 period from January 1833 to April 2018, a long period of time in which in-
68 terest rates have shown a very heterogeneous behaviour, with stable interest
69 rates at the beginning of the sample period and with more volatile interest
70 rates from the second half of the 20th century to the end of the sample.

71 The remainder of this paper is organised as follows. Section 2 describes
72 the different models that will be used to forecast UK interest rate volatility.
73 Section 3 presents and discusses the empirical results. Finally, Section 4

74 summarizes and concludes this study.

75 2. Model Description

76 2.1. Univariate GARCH Models

77 **GARCH:** The standard GARCH model formulates the conditional vari-
78 ance of a stochastic process $\{\varepsilon_t\}$ as follows (Bollerslev, 1986):

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \sigma_t^2 &= \text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = \alpha_0 + \sum_{i=1}^q \alpha_i \varepsilon_{t-i}^2 + \sum_{i=1}^p \beta_i \sigma_{t-i}^2,\end{aligned}$$

79 where $E(\varepsilon_t | \mathcal{F}_{t-1}) = 0$ and \mathcal{F}_{t-1} is the σ -field containing all the information
80 available at time t . Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with
81 mean zero and variance 1. Bollerslev (1986) considers the conditional distri-
82 bution of $\varepsilon_t | \mathcal{F}_{t-1}$ to be normal, however other distributions could be applied.
83 In GARCH formulation, the $\{\varepsilon_t\}$ process has zero mean. In the case that
84 process has time variant conditional mean, one may use an ARMA process
85 to remove the conditional mean, and then apply the GARCH to model the
86 conditional variance. In this case the model is called ARMA-GARCH and is
87 formulated as follows:

$$\begin{aligned}y_t - \phi_0 - \left(\sum_{i=1}^r \phi_i y_{t-i}\right) - \left(\sum_{i=1}^m \theta_i \varepsilon_{t-i}\right) &= \varepsilon_t = \sigma_t Z_t, \\ \text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = \sigma_t^2 &= \alpha_0 + \sum_{i=1}^q \alpha_i \varepsilon_{t-i}^2 + \sum_{i=1}^p \beta_i \sigma_{t-i}^2.\end{aligned}$$

88 **A-PARCH:** The general structure of Asymmetric Power ARCH (A-
89 PARCH) model is as follows (Ding et al., 1993):

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \sigma_t^\delta &= \alpha_0 + \sum_{i=1}^q \alpha_i (|\varepsilon_{t-i}| - \gamma_i \varepsilon_{t-i})^\delta + \sum_{i=1}^p \beta_i \sigma_{t-i}^\delta,\end{aligned}$$

90 where Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
91 variance 1, $\alpha_0 > 0$, $\alpha_i, \delta, \beta_i \geq 0$ and $-1 < \gamma_i < 1$. The model imposes

92 a Box-Cox power transformation and the asymmetric absolute residuals to
 93 handle the asymmetric behavior and Taylor effect¹.

94 **CGARCH:** The Component GARCH (CGARCH) model (Engle and
 95 Lee, 1999) decompose the conditional variance to transitory and permanent
 96 components:

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \sigma_t^2 &= Var(\varepsilon_t | \mathcal{F}_{t-1}) = c_t + \sum_{i=1}^q \alpha_i (\varepsilon_{t-i}^2 - c_{t-i}) + \sum_{i=1}^p \beta_i (\sigma_{t-i}^2 - c_{t-i}), \\ c_t &= \alpha_0 + \rho c_{t-1} + \gamma (\varepsilon_{t-1}^2 - \sigma_{t-1}^2),\end{aligned}$$

97 where Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
 98 variance 1 and c_t is the permanent component. Using both permanent and
 99 transitory components, the CGARCH model has the ability to explain long
 100 term and short term movements in volatility.

101 **EGARCH:** The Exponential GARCH (EGARCH) model of Nelson (1991)
 102 is defined as follows:

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \ln(\sigma_t^2) &= \ln(Var(\varepsilon_t | \mathcal{F}_{t-1})) = \alpha_0 + \sum_{i=1}^q \left(\alpha_i z_{t-i} + \gamma_i (|z_{t-i}| - E(|Z_{t-i}|)) \right) \\ &\quad + \sum_{i=1}^p \beta_i \ln(\sigma_{t-i}^2),\end{aligned}$$

103 where Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
 104 variance 1 and $E(|Z_t|)$ is the conditional expectation with respect to density
 105 function $f(z)$:

$$E(|Z_t|) = \int_{-\infty}^{\infty} |z| f(z) dz.$$

106 The EGARCH model, captures the asymmetric behavior in time series,
 107 through the term $g(z_{t-i}) = \alpha_i z_{t-i} + \gamma_i (|z_{t-i}| - E(|Z_{t-i}|))$. The ARCH effect
 108 term, $g(z_t)$ is linear in z_t with slope $\alpha + \gamma$ for $z_t > 0$ and $\alpha - \gamma$ for $z_t < 0$
 109 (Nelson, 1991).

¹ Taylor (1986) showed in some financial time series, the sample autocorrelation of absolute returns was larger than that of squared returns.

110 **GJR-GARCH:** [Golsten et al. \(1993\)](#), used an indicator function to ex-
 111 plain the positive and negative shocks effect on volatility. Assuming the pro-
 112 cess has zero conditional mean, the Golsten, Jagannathan, Runkle GARCH
 113 (GJR-GARCH) model is formulated as follows:

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \sigma_t^2 &= \alpha_0 + \sum_{i=1}^q (\alpha_i \varepsilon_{t-i}^2 - \gamma_i I_{t-i} \varepsilon_{t-i}^2) + \sum_{i=1}^p \beta_i \sigma_{t-i}^2,\end{aligned}$$

114 where Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
 115 variance 1 and the indicator function I_t takes on values 1 for positive values
 116 of ε_t and zero otherwise.

117 **TGARCH:** The Threshold GARCH (TGARCH) process is given by [Za-](#)
 118 [koian, 1994](#)):

$$\begin{aligned}\varepsilon_t &= \sigma_t Z_t, \\ \sigma_t &= (\text{Var}(\varepsilon_t | \mathcal{F}_{t-1}))^{1/2} = \alpha_0 + \sum_{i=1}^q (\alpha_i^+ \varepsilon_{t-i}^+ - \alpha_i^- \varepsilon_{t-i}^-) + \sum_{i=1}^p \beta_i \sigma_{t-i},\end{aligned}$$

119 where Z_t is a white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
 120 variance 1, $\varepsilon_t^+ = \max(\varepsilon_t, 0)$, $\varepsilon_t^- = \min(\varepsilon_t, 0)$ and α_i^+ , α_i^- and β_i are real
 121 scalars. The TGARCH model uses different sets of coefficient to explain the
 122 rise and fall of the process. Using this feature, the TGARCH process has the
 123 ability to explain asymmetric behavior in financial time series.

124 2.2. Error Distributions in Univariate GARCH Models

125 As mentioned before, the common choice for error term distributions in
 126 variation of GARCH models are Normal and Student's t distributions. How-
 127 ever, There are other choices which have the ability to capture the heavy
 128 tailed and asymmetric behavior in standardized residuals. The error dis-
 129 tributions considered in this paper (provided by rugarch package) are Nor-
 130 mal, Student's t, Generalized Error Distribution (GED), Skew Normal (SN),
 131 Skew Student's t (SSt), Skew Generalized Error Distribution (SGED), Inverse
 132 Gaussian (IG), Generalized Hyperbolic (GH) and Johnson's SU Distribution
 133 (JSU).

134 *2.3. ARMA - Generalized Additive Semiparametric GARCH*

135 The ARMA Generalized Additive Semiparametric GARCH (ARMA-GASGARCH)
 136 models the conditional mean and variance of a stochastic process as follows:

$$y_t - \phi_0 - \left(\sum_{i=1}^r \phi_i y_{t-i} \right) - \left(\sum_{i=1}^m \theta_i \varepsilon_{t-i} \right) = \varepsilon_t = \sigma_t Z_t,$$

$$\text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = \sigma_t^2 = f_1(\varepsilon_{t-1}) + f_2(\sigma_{t-1}^2) + f_3(y_{t-1}).$$

137 where Z_t is white noise, independent of \mathcal{F}_{t-1} for all t with mean zero and
 138 variance 1 and $f_i(\cdot)$, ($i = 1, 2, 3$) are nonlinear univariate functions. The
 139 GASGARCH process given by [Hou and Suardi \(2011\)](#) considers the condi-
 140 tional mean to be fixed over the time and applies the nonparametric GARCH
 141 ([Bühlmann and McNeil, 2002](#)) model to estimate the nonlinear functions. In
 142 this paper, the same idea is developed to the models with ARMA condi-
 143 tional mean (which is the parametric component of the model). Following
 144 the [Bühlmann and McNeil \(2002\)](#) and [Hou and Suardi \(2011\)](#), an ARMA
 145 model is applied for to model the conditional mean and a nonlinear addi-
 146 tive model is applied to build the conditional variance model. The nonlinear
 147 functions $f_i(\cdot)$ are estimated using local linear kernel estimation (the band-
 148 width selection is carried out based on [Li and Racine, 2004](#)). Assuming,
 149 Z_t ($t = 1, \dots, n$) are iid random variables, one may use a kernel density es-
 150 timation to estimate the innovations' distribution function. In this paper,
 151 nonparametric estimation are given based on Epanechnikov kernel function.

152 *2.4. Mixture Autoregressive Model*

153 The Mixture Autoregressive model (MAR) of [Wong and Li \(2000\)](#), for-
 154 mulates the conditional distribution of stochastic process $\{y_t\}$ as follows:

$$F(y_t | \mathcal{F}_{t-1}) = \sum_{k=1}^K \alpha_k \Phi \left(\frac{y_t - \phi_{k0} - \sum_{i=1}^{p_k} \phi_{ki} y_{t-i}}{\sigma_k} \right), \quad (1)$$

155 where $F(y_t | \mathcal{F}_{t-1})$ is the conditional distribution function of the y_t given
 156 past information, Φ denotes the Standardized Normal cumulative distribu-
 157 tion function and \mathcal{F}_{t-1} is the σ -field representing all available information
 158 trough time t . The mixing weights $\alpha_1, \dots, \alpha_K$ satisfies following conditions:

$$\alpha_k > 0, k = 1, \dots, K,$$

$$\sum_{k=1}^K \alpha_k = 1.$$

159 The formulation of MAR is a mixture of AR components with constant
160 conditional variances. However, the MAR model as the flexibility to model
161 time variant conditional variance as well as multi modal, heavy tail, asym-
162 metry and changes in the shape of forecasting distribution. Based on condi-
163 tional distribution (1), the conditional mean and variance of the model can
164 be formulated as:

$$E(y_t | \mathcal{F}_{t-1}) = \sum_{k=1}^K \alpha_k \left(\phi_{k0} + \sum_{i=1}^{p_k} \phi_{ki} y_{t-i} \right) = \sum_{k=1}^K \alpha_k \mu_{k,t} ,$$

$$Var(y_t | \mathcal{F}_{t-1}) = \sum_{k=1}^K \alpha_k \sigma_k^2 + \sum_{k=1}^K \alpha_k \mu_{k,t}^2 - \left(\sum_{k=1}^K \alpha_k \mu_{k,t} \right)^2 .$$

165 2.5. Forecasting Evaluation

166 Suppose $\hat{\sigma}_{t+h}$ is the h step ahead volatility forecast and the ε_{t+h} is the
167 residual of the conditional mean model at time t :

$$\varepsilon_{t+h} = y_{t+h} - E(y_{t+h} | \mathcal{F}_t),$$

$$\hat{\sigma}_{t+h} = \widehat{Var}(y_{t+h} | \mathcal{F}_t).$$

168 The root mean square error, RMSE, measures the accuracy of the forecast:

$$RMSE = \left(\frac{1}{n} \sum_{t=1}^n \eta_{t+h} \right)^{\frac{1}{2}} ,$$

169 where η_{t+h} is the h step ahead square error of volatility forecasting:

$$\eta_{t+h} = (|\varepsilon_{t+h}| - \hat{\sigma}_{t+h})^2$$

170 In order to compare the accuracy of forecasting models, one may use the
171 Kolmogorov-Smirnov Predictive Accuracy, KSPA, test. The two sided KSPA
172 tests the following hypothesis (Hassani and Silva, 2015):

$$\begin{cases} H_0 : F_{\eta_{i+h}^{(1)}}(z) = F_{\eta_{i+h}^{(2)}}(z) \\ H_1 : F_{\eta_{i+h}^{(1)}}(z) \neq F_{\eta_{i+h}^{(2)}}(z) \end{cases} ,$$

173 where $F_{\eta_{i+h}^{(k)}}(\cdot)$ is the distribution function of square error corresponding to
174 k th forecasting model. The rejection of the null hypothesis concludes that
175 two models doesn't share the same forecasting accuracy.

Table 1: The results of Augmented Dickey-Fuller Test

Series' Name	Time Series' Variance	Parameter (Lag order)	Statistic	P-value
BR	9.0425	20	-1.6682	0.0902
BR's First Difference	0.3263	20	-12.1211	< 2.2e-16

176 **3. Empirical Results**

177 Our variable of interest is the monetary policy instrument of the Bank
178 of England (BoE), called the Bank Rate. Our sample covers the period
179 of May 1836 to June 2018. Note that even though the monthly data on
180 the Bank Rate (BR) is available from November 1694, the data remained
181 virtually constant until the beginning of our sample period, and hence, we
182 decided to ignore the early part of the available data. The data is sourced
183 from "A Millennium of Macroeconomic Data for the UK" - a database main-
184 tained by the BoE at: [https://www.bankofengland.co.uk/statistics/
185 research-datasets](https://www.bankofengland.co.uk/statistics/research-datasets). Figure 1 shows the bank rate from May 1836 to June
186 2018 and its Autocorrelation Function (ACF) and Partial Autocorrelation
187 Function (PACF). Since the ACF shows nonstationary behavior, the sta-
188 tionarity of the time series is tested using Augmented Dickey-Fuller Test
189 (MacKinnon, 1996).² Table 1 shows the result of the test for the original
190 time series and its first-difference. According to the Table 1, the BR data
191 is non-stationary (the null hypothesis of the test is retained at the 5% level
192 of significance), however, the first-difference of the BR is stationary. Fig-
193 ure 2 plots the first-differenced version of the BR (dRB) variable and the
194 corresponding ACF and PACF.

195

196

197 The RMSE for out-of-sample volatility forecasting of the different models
198 are presented in detail in Tables 2 and 3. Table 4 summarizes the models

²The test is applied using the "fUnitRoots" package in R.

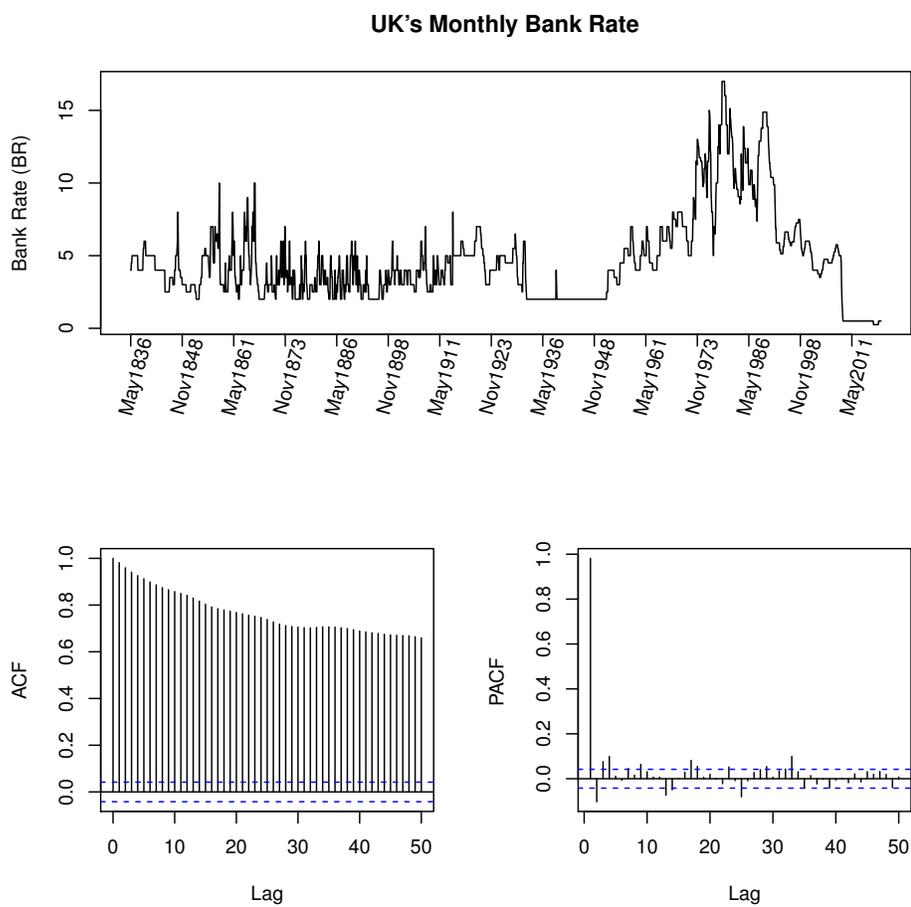


Figure 1: BR time series and its ACF and PACF.

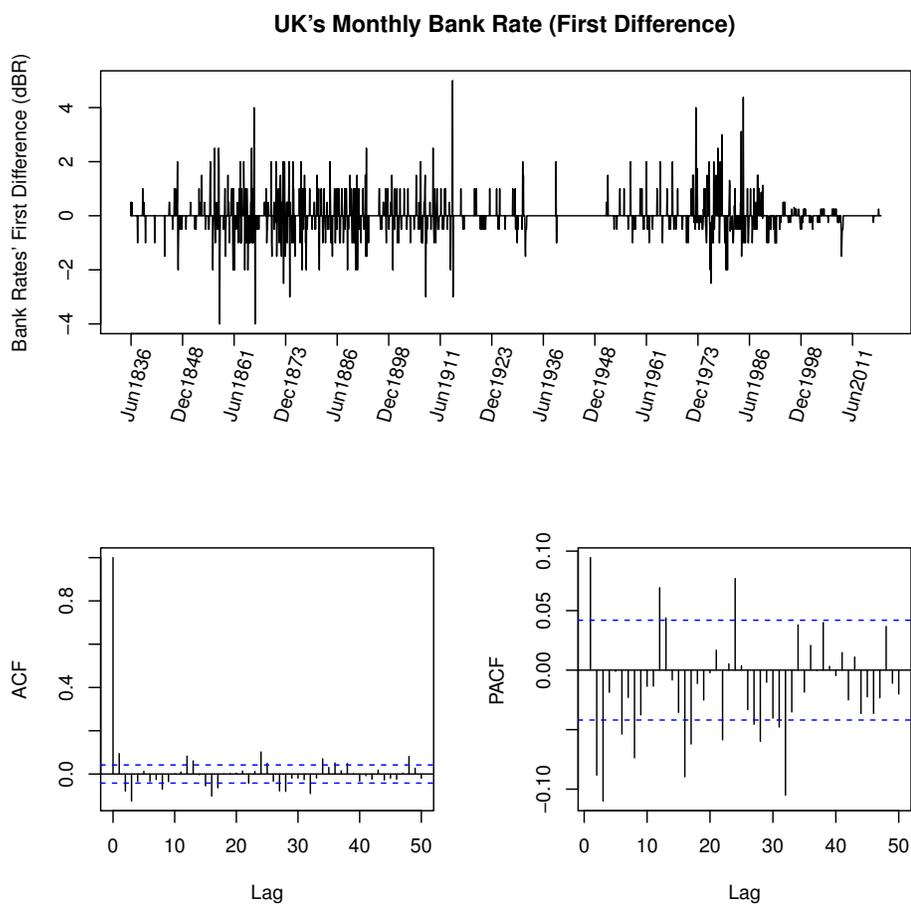


Figure 2: First-difference of the BR (dBR) time series and its ACF and PACF.

199 with minimum RMSE for very short- ($h=1$), short- ($h=3$), medium- ($h=6$)
200 and long-terms ($h=12$) out-of-sample horizons associated with volatility fore-
201 casting. The ARMA-A-PARCH model with SGED error distribution gives
202 the most accurate volatility forecasts for the very short-term horizon and
203 the GARCH model with GED error distribution for short-, medium- and
204 long-term horizons, in terms of minimum RMSE.

205 The KSPA test is applied to compare accuracy of different models with
206 the minimum RMSE model (Table 4). The p-values of the test is given in
207 Table 5 and 6. The results show that at the very-short forecasting horizon,
208 the most accurate models either have asymmetric behavior (A-PARCH) or
209 asymmetric distribution (SGED and JSU). At other forecasting horizons,
210 however, the performance of the symmetric GARCH model with symmetric
211 distribution is not statistically different from the asymmetric models with
212 asymmetric distributions. The summary of the KSPA tests are presented
213 in Table 7. As can be seen, none of the models with accuracy same as the
214 minimum RMSE models has normal distributions, which in turn shows the
215 importance of heavy-tailed behavior at all forecasting horizons.

216 4. Conclusion

217 The main objective of this paper is to evaluate the very short, medium
218 and long-term forecasting ability of different univariate GARCH models of
219 UK interest rate volatility, using a long span monthly data from May 1836
220 to June 2018. With this purpose, we calculate the forecasting ability of dif-
221 ferent univariate GARCH- type models (GARCH, Threshold GARCH, Ex-
222 ponential GARCH, Component GARCH, and Asymmetric Power ARCH).
223 Furthermore, when using these GARCH-type models, we try to capture the
224 heavy tailed and asymmetric behaviour using alternative error term distri-
225 butions, such as Normal, Students t, Generalized Error Distribution (GED),
226 Skew Normal (SN), Skew Students (SSt), Skew Generalized Error Distri-
227 bution (SGED), Inverse Gaussian (IG), Generalized Hyperbolic (GH) and
228 Johnsons SU Distribution (JSU), ARMA-Generalized Additive Semipara-
229 metric GARCH by Hou and Suardi (2011) and the Mixture Autoregressive
230 Model by Wong and Li (2000) are also used to forecast UK interest rates.

231 Although the results suggest that the forecasting accuracy of each of the
232 models depends on the forecasting horizon, they clearly show the relevance

Table 2: Out-of-sample volatility forecasting RMSE of dBR

Model	h = 1	h = 3	h = 6	h = 12
GARCH (Normal) ^a	0.5030	0.4940	0.5010	0.5240
GARCH (SN) ^a	0.4464	0.4615	0.4792	0.5099
GARCH (Student's t) ^a	0.6475	0.9610	1.9800	8.7328
GARCH (SSt) ^a	0.5188	0.5148	0.5083	0.5039
GARCH (GED) ^a	0.4077	0.4039	0.3994	0.3941
GARCH (SGED) ^a	0.4181	0.4171	0.4149	0.4113
GARCH (IG) ^a	0.4226	0.4334	0.4460	0.4550
GARCH (GH) ^a	0.4337	0.4394	0.4190	0.4090
GARCH (JSU) ^a	0.4065	0.4061	0.4037	0.4000
TGARCH (Normal) ^a	0.5331	0.5401	0.5520	0.5750
TGARCH (SN) ^a	0.5306	0.5384	0.5640	0.6179
TGARCH (Student's t) ^a	0.7599	0.7579	0.4729	0.4579
TGARCH (SSt) ^a	0.5284	0.5252	0.4590	0.4604
TGARCH (GED) ^a	1.3561	1.3523	1.3477	1.3388
TGARCH (SGED) ^a	6.1216	6.1216	6.1216	6.1216
TGARCH (IG) ^a	0.4464	0.4653	0.4410	0.4520
TGARCH (GH) ^a	6.1216	6.1216	6.1200	6.1200
TGARCH (JSU) ^a	3.3909	2.0135	0.4577	0.4597
EGARCH (Normal) ^a	. ^b	. ^b	8.04E+13	1.38E+12
EGARCH (SN) ^a	0.5530	0.5386	0.5146	0.5614
EGARCH (Student's t) ^a	. ^b	. ^b	. ^b	. ^b
EGARCH (SSt) ^a	540.1583	8.9836	0.4559	0.4590
EGARCH (GED) ^a	. ^b	. ^b	. ^b	. ^b
EGARCH (SGED) ^a	. ^b	. ^b	. ^b	. ^b
EGARCH (IG) ^a	. ^b	. ^b	2.19E+18	4.35E+16
EGARCH (GH) ^a	. ^b	. ^b	5.75E+26	8.58E+33
EGARCH (JSU) ^a	0.8292	0.7893	0.7737	0.7589

^a. The conditional mean model is ARMA.

^b. The value is computationally infinite.

Table 3: Out-of-sample volatility forecasting RMSE for dBR (Continued)

Model	h = 1	h = 3	h = 6	h = 12
CGARCH (Normal) ^a	0.4174	0.4484	0.4560	0.4660
CGARCH (SN) ^a	0.4402	0.4556	0.4721	0.4871
CGARCH (Student's t) ^a	0.4820	0.4365	0.4272	0.4383
CGARCH (SSt) ^a	0.4557	0.4369	0.4423	0.4595
CGARCH (GED) ^a	0.4348	0.4306	0.4287	0.4253
CGARCH (SGED) ^a	0.4410	0.4290	0.4224	0.4117
CGARCH (IG) ^a	0.4392	0.4480	0.4550	0.4560
CGARCH (GH) ^a	0.4332	0.4148	0.4150	0.4270
CGARCH (JSU) ^a	0.5738	0.5747	0.5755	0.5770
A-PARCH (Normal) ^a	0.4694	0.4767	0.4950	0.5170
A-PARCH (SN) ^a	0.4636	0.4751	0.4910	0.5328
A-PARCH (Student's t) ^a	0.4235	0.4271	0.4259	0.4322
A-PARCH (SSt) ^a	0.9808	0.6871	0.4836	0.4464
A-PARCH (GED) ^a	1.7951	1.6933	1.5227	1.2562
A-PARCH (SGED) ^a	0.4051	0.4043	0.4020	0.3992
A-PARCH (IG) ^a	0.4187	0.4200	0.4230	0.4300
A-PARCH (GH) ^a	0.4099	0.4119	0.4170	0.4370
A-PARCH (JSU) ^a	0.4062	0.4058	0.4024	0.3981
GJR-GARCH (Normal) ^a	0.4665	0.4680	0.4720	0.4880
GJR-GARCH (SN) ^a	0.5026	0.4956	0.4976	0.5214
GJR-GARCH (Student's t) ^a	0.5389	0.4647	0.4432	0.4491
GJR-GARCH (SSt) ^a	0.5459	0.5229	0.5001	0.4692
GJR-GARCH (GED) ^a	0.4306	0.4314	0.4304	0.4315
GJR-GARCH (SGED) ^a	0.4161	0.4144	0.4113	0.4076
GJR-GARCH (IG) ^a	0.5143	0.4445	0.4330	0.4450
GJR-GARCH (GH) ^a	0.4387	0.4138	0.4050	0.4020
GJR-GARCH (JSU) ^a	0.6323	0.6388	0.6491	0.6801
GASGARCH ^a	10.3293	24.1132	4.26E+13	2.2347
MAR	0.5838	0.5877	0.5944	0.6223

^a. The conditional mean model is ARMA.

Table 4: Minimum RMSE models for forecasting dBR volatility

	h=1	h=3	h=6	h=12
Model	A-PARCH	GARCH	GARCH	GARCH
Error distribution	SGED	GED	GED	GED
RMSE value	0.4051	0.4039	0.3994	0.3941

233 of considering alternative error distributions to the normal distribution when
 234 estimating GARCH-type models. For example, for the very short-term fore-
 235 casting horizon ($h=1$), A-PARCH models with skew generalized error dis-
 236 tribution are the most accurate models when forecasting UK interest rates,
 237 while for short, medium and long-term term forecasting horizons ($h=3$ and
 238 $h=6$, $h=12$), GARCH models with generalized error distribution for the error
 239 term are the most accurate models.

240 The results on the forecasting ability of these models should be taken
 241 into account when forecasting interest rates for portfolio diversification, in-
 242 vestment or hedging strategies, for pricing different financial securities, for
 243 risk managers, or for forecasting different macroeconomic variables depen-
 244 dent on interest rates.

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Table 5: *KSPA* test p-values (two-tailed) for comparing the out-of-sample forecasts to minimum RMSE of dBR volatility forecast

	h = 1	h = 3	h = 6	h = 12
Minimum RMSE model →	A-PARCH	GARCH	GARCH	GARCH
Comparing to ↓	(SGED) ^a	(GED) ^a	(GED) ^a	(GED) ^a
GARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
GARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
GARCH(Student's t) ^a	0.0000	0.0000	0.0000	0.0000
GARCH(SSt) ^a	0.0000	0.0001	0.0000	0.0000
GARCH(GED) ^a	0.0153			
GARCH(SGED) ^a	0.0017	0.0828	0.0921	0.0023
GARCH(IG) ^a	0.0291	0.0199	0.0226	0.0000
GARCH(GH) ^a	0.0066	0.1023	0.0419	0.0199
GARCH(JSU) ^a	0.0665	0.5235	0.7015	0.1530
TGARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
TGARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
TGARCH(Student's t) ^a	0.0000	0.0000	0.0000	0.0000
TGARCH(SSt) ^a	0.0000	0.0001	0.0001	0.0000
TGARCH(GED) ^a	0.0000	0.0000	0.0000	0.0000
TGARCH(SGED) ^a	0.0000	0.0010	0.0001	0.0000
TGARCH(IG) ^a	0.0001	0.0076	0.0291	0.0001
TGARCH(GH) ^a	0.0000	0.0010	0.0001	0.0000
TGARCH(JSU) ^a	0.0000	0.0000	0.0001	0.0000
EGARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(Student's t) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(SSt) ^a	0.0000	0.0007	0.0001	0.0000
EGARCH(GED) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(SGED) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(IG) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(GH) ^a	0.0000	0.0000	0.0000	0.0000
EGARCH(JSU) ^a	0.0000	0.0000	0.0000	0.0000

^a. The conditional mean model is ARMA.

Table 6: *KSPA* test p-values (continued)

	h = 1	h = 3	h = 6	h = 12
Minimum RMSE model → Comparing to ↓	A-PARCH (SGED) ^a	GARCH (GED) ^a	GARCH (GED) ^a	GARCH (GED) ^a
CGARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
CGARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
CGARCH(Student's t) ^a	0.0000	0.0921	0.1256	0.0116
CGARCH(SSt) ^a	0.0002	0.0830	0.0362	0.0001
CGARCH(GED) ^a	0.0000	0.0199	0.0014	0.0002
CGARCH(SGED) ^a	0.0000	0.0742	0.0594	0.0199
CGARCH(IG) ^a	0.0014	0.0199	0.0005	0.0000
CGARCH(GH) ^a	0.0057	0.0007	0.0000	0.0004
CGARCH(JSU) ^a	0.0000	0.0000	0.0000	0.0000
A-PARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
A-PARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
A-PARCH(Student's t) ^a	0.0006	0.0665	0.0372	0.0007
A-PARCH(SSt) ^a	0.0000	0.0002	0.0027	0.0001
A-PARCH(GED) ^a	0.0000	0.0000	0.0000	0.0000
A-PARCH(SGED) ^a		0.0828	0.0665	0.1850
A-PARCH(IG) ^a	0.0199	0.0012	0.0101	0.0257
A-PARCH(GH) ^a	0.0020	0.0004	0.0594	0.0003
A-PARCH(JSU) ^a	0.0076	0.0101	0.0057	0.1135
GJR-GARCH(Normal) ^a	0.0000	0.0000	0.0000	0.0000
GJR-GARCH(SN) ^a	0.0000	0.0000	0.0000	0.0000
GJR-GARCH(Student's t) ^a	0.0000	0.0027	0.0043	0.0001
GJR-GARCH(SSt) ^a	0.0000	0.0020	0.0012	0.0001
GJR-GARCH(GED) ^a	0.0004	0.0594	0.0291	0.0002
GJR-GARCH(SGED) ^a	0.0023	0.3813	0.0549	0.0488
GJR-GARCH(IG) ^a	0.0000	0.0257	0.0372	0.0031
GJR-GARCH(GH) ^a	0.0000	0.1758	0.2532	0.3261
GJR-GARCH(JSU) ^a	0.0000	0.0000	0.0000	0.0000
GASGARCH ^a	0.0000	0.0000	0.0000	0.0000
MAR	0.0000	0.0000	0.0000	0.0000

^a. The conditional mean model is ARMA.

Table 7: Forecasts similar to the Minimum RMSE of dBR volatility forecasting (H_0 Retained at 0.05 significance level).

Minimum RMSE model →	h = 1	h = 3	h = 6	h = 12
	A-PARCH (SGED) ^a	GARCH (GED) ^a	GARCH (GED) ^a	GARCH (GED) ^a
	GARCH (JSU) ^a	GARCH (SGED) ^a	GARCH (SGED) ^a	GARCH (JSU) ^a
		GARCH (GH) ^a	GARCH (JSU) ^a	A-PARCH (SGED) ^a
		GARCH (JSU) ^a	CGARCH (Student's t) ^a	A-PARCH (JSU) ^a
		CGARCH (Student's t) ^a	CGARCH (SGED) ^a	GJR-GARCH (GH) ^a
		CGARCH (SSt) ^a	A-PARCH (SGED) ^a	
		CGARCH (SGED) ^a	A-PARCH (GH) ^a	
		A-PARCH (Student's t) ^a	GJR-GARCH (SGED) ^a	
		A-PARCH (SGED) ^a	GJR-GARCH (GH) ^a	
		GJR-GARCH (GED) ^a		
		GJR-GARCH (SGED) ^a		
		GJR-GARCH (GH) ^a		

^a. The conditional mean model is ARMA.

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